

# Smooth Kuranishi atlases

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**SPECIAL SESSION: ADVANCES IN SYMPLECTIC  
GEOMETRY AND TOPOLOGY**

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This is a talk about my ongoing project with **Katrin Wehrheim** [MW1,2] to clarify the construction of the virtual moduli cycle in the Gromov–Witten context. **Basic question**: how can one count closed  $J$ -holomorphic curves in a symplectic manifold in a way that is independent of choices?

The talk will be divided into several parts.

Part 1: Explanation of the problem.

Part 2: Kuranishi atlases.

Part 3: Building charts with isotropy.

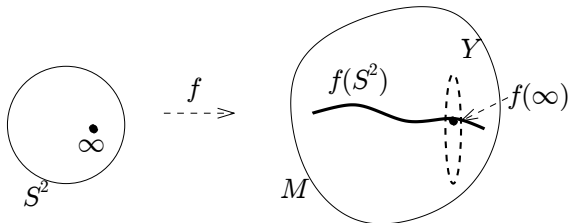
## Counting $J$ -holomorphic spheres:

3.

$(M^{2n}, \omega, J)$  is a symplectic manifold with an  $\omega$ -tame almost complex structure  $J$ . We want to count the number of  $J$ -holomorphic maps  $f : (S^2, j) = (\mathbb{C} \cup \infty, j) \rightarrow (M, J)$ , with  $f_*([S^2]) = A \in H_2(M, \mathbb{Z})$  (modulo parametrization) that satisfy certain homological constraints: e.g. if  $Y \subset M$  is a submanifold, count

$$\# \left( \{f \mid 0 = \bar{\partial}_J f =: \frac{1}{2}(df + J \circ f \circ j), f(\infty) \in Y\} / G_\infty \right)$$

where  $G_\infty$  is the group of reparametrizations  $z \mapsto az + b$  fixing  $\infty$ .



# The virtual fundamental class VFC:

4.

More abstractly, we would like to show that the **space of solutions  $X$  to the Fredholm equation  $\bar{\partial}_J f = 0$ ,  $f_*([S^2]) = A$**  has a homology class

$$[X]^{\text{vir}} \in H_d(X)$$

(in the dimension  $d$  of the index of the Fredholm operator).

Then the count would just be the intersection number  $\text{ev}_*([X]^{\text{vir}}) \cdot_M [Y]$  where  $\text{ev}$  is the evaluation map  $\text{ev}(f) = f(\infty)$ .

In the **semi-positive case**, one can often choose  $J$  so that  $X$  is a manifold of dimension  $d$ ; if noncompact, it often still has “boundary” of codimension  $\geq 2$ , so that  **$\text{ev} : X \rightarrow M$  represents a well defined homology class** (independent of choice of  $J$ ).

## Problems with the naive (geometric) approach: 5.

- ▶ **Nonregular  $J$ :** Even if  $J$  is generic, the space of **solutions**  $X := \mathcal{M}_{0,1}(A, J)$  to the **Fredholm equation**  $\bar{\partial}_J f = 0$ ,  $f_*([S^2]) = A$  is not usually a manifold of the right dimension (i.e. equal to the Index of  $\bar{\partial}_J$ ).
- ▶ **Existence of isotropy:** Some solutions have an internal symmetry (e.g.  $f : z \mapsto z^2$  is invariant under the action of  $\mathbb{Z}/2\mathbb{Z}$  by  $z \mapsto -z$ ). So  $X := \mathcal{M}_{0,1}(A, J)$  has to be given some kind of **orbifold structure**.
- ▶ **Lack of compactness:** Usually one must compactify the solution space by adding **nodal curves** that then must be glued together, greatly complicating the required analysis.
- ▶ **Lack of smoothness:** One must use Banach space of maps  $f : S^2 \rightarrow M$  (e.g.  $W^{k,p}$ -maps) to do Fredholm analysis, but the reparametrization group **does not act differentiably** on such a space.

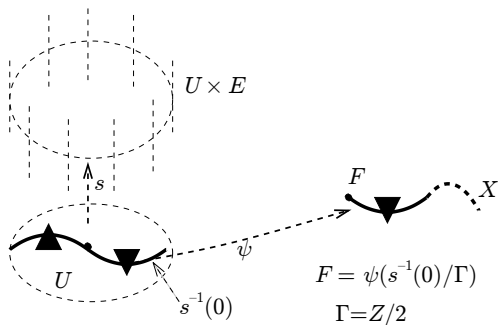
In 1990s, great progress with these issues by Li-Tian, Fukaya–Ono and others (Ruan, Siebert, ...). Emphasis on gluing analysis; sketchy treatment of **smoothness/topological issues** in constructing charts, VFC.

- ▶ **Polyfolds:** Hofer–Wysocki–Zehnder (2006 –now ) series of papers completely redoing the analytic foundations. Gromov–Witten preprint: arxiv 1107.2097
- ▶ **Smooth Kuranishi atlases:** McDuff–Wehrheim, arXiv 1208.1340: recast the basic definitions of FO, FOOO in more categorical terms; redid the topological aspects of the proof in a special case (no nodes, no isotropy).
- ▶ **Detailed treatment of Kuranishi structures:** Fukaya–Oh–Ohta–Ono, arXiv 1209.4410; *many* more details of the general case, including smoothness of gluing.
- ▶ **New, wholistic approach using “Donaldson divisors”:** Ionel–Parker, arXiv 1304.3472; more geometric approach initially suggested by Cieliebak–Mohnke.
- ▶ **Reworking of the Tian approach using “virtual manifolds”:** Chen–Li–Wang, arXiv 1306.3276. new way of dealing with the nonsmooth action.

## Finite dimensional reductions [FO], [FOOO], [MW], [CLW]: 7.

The moduli space  $X$  can be locally modelled by a **finite dimensional reduction**  $(U, E, \Gamma, s, \psi)$ , where

- ▶ the **domain**  $U$  is a smooth manifold, the **obstruction space**  $E \cong \mathbb{R}^n$ ;
- ▶ the **isotropy group**  $\Gamma$  is a finite group acting diagonally on  $U \times E$ ;
- ▶ the **section**  $s : U \rightarrow E$  is induced by  $\bar{\partial}_J$ , and is  $\Gamma$ -equivariant;
- ▶ the **footprint map**  $\psi : s^{-1}(0) \rightarrow X$  induces a homeomorphism  $s^{-1}(0)/\Gamma \rightarrow F$ , where  $F \subset X$  is open.



Let  $X$  be a compact, metrizable space. A **Kuranishi chart** for  $X$  with footprint  $F$  is a tuple  $\mathbf{K} = (U, E, \Gamma, s, \psi)$  with  $F = \text{im } \psi$ .

- ▶ A **covering family of basic charts** for  $X$  is a finite collection  $(\mathbf{K}_i)_{i=1, \dots, N}$  of Kuranishi charts with  $X = \bigcup_{i=1}^N F_i$ .
- ▶ **Transition data** for  $(\mathbf{K}_i)_{i=1, \dots, N}$  is a collection of charts  $(\mathbf{K}_J)_{J \in \mathcal{I}_K, |J| \geq 2}$  and coordinate changes  $(\widehat{\Phi}_{IJ})_{I, J \in \mathcal{I}_K, I \subsetneq J}$  as follows:
  1.  $\mathcal{I}_K$  is the set of subsets  $I \subset \{1, \dots, N\}$  s.t.  $F_I := \bigcap_{i \in I} F_i \neq \emptyset$ ;
  2. the sum chart  $\mathbf{K}_J$  has footprint  $F_J = \bigcap_{i \in J} F_i$  and additive obstruction space  $E_J \cong \bigoplus E_{i \in J}$ ; (in GW case must be built using some analysis)
  3. all charts have the **same dimension**  $d := \dim U_I - \dim E_I = \text{Ind}(\overline{\partial}_J)$  (so  $\dim U_I \leq \dim U_J$  if  $I \subset J$ .)
  4.  $\widehat{\Phi}_{IJ}$  is a coordinate change  $\mathbf{K}_I \rightarrow \mathbf{K}_J$  for every  $I, J \in \mathcal{I}_K$  with  $I \subsetneq J$ . (to be explained)

A **Kuranishi atlas**  $\mathcal{K}$  on  $X$  consists of  $(\mathbf{K}_J, \widehat{\Phi}_{IJ})$  as above satisfying the **cocycle condition**. (to be explained)

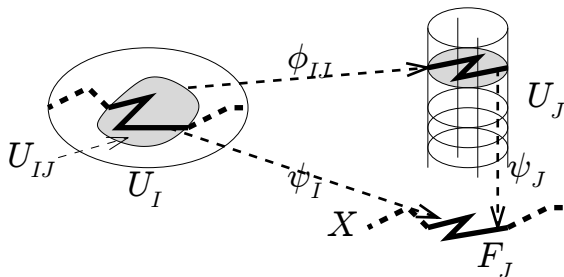


## Coordinate changes I (no isotropy):

9.

If  $I \subset J$  then  $F_I \supset F_J$  and there is a **coordinate change**  $\mathbf{K}_I \rightarrow \mathbf{K}_J$ , consisting of a **restriction**  $\mathbf{K}_I \rightarrow \mathbf{K}_I|_{U_{IJ}}$  followed by an **inclusion**  $\mathbf{K}_I|_{U_{IJ}} \rightarrow \mathbf{K}_J$  induced by an **embedding**  $\phi_{IJ} : U_{IJ} \rightarrow U_J$ , where

- ▶  $U_{IJ} \subset U_I$  (in grey) intersects the zero set  $s_I^{-1}(0)$  in  $\psi_I^{-1}(F_J)$ ;
- ▶ the (grey) image of  $\phi_{IJ} : U_{IJ} \rightarrow U_J$  is a smooth submanifold with “nice” normal bundle;
- ▶ there is an associated **linear inclusion**  $\hat{\phi}_{IJ} : E_I \rightarrow E_J$ ;
- ▶ obvious **compatibility conditions** with footprint maps and sections; (eg for  $x \in \psi_I^{-1}(F_J)$ , we have  $\psi_J \circ \phi_{IJ}(x) = \psi_I(x) \in F_J$ )



## Cocycle condition and Kuranishi category (no isotropy) : 10.

**Aim:** each atlas  $\mathcal{K}$  should have **domain and bundle categories** with functor  $\text{proj} : \mathbf{E}_{\mathcal{K}} \rightarrow \mathbf{B}_{\mathcal{K}}$ , where  $\text{Obj}_{\mathbf{B}_{\mathcal{K}}} = \bigcup_I U_I$  and the morphisms  $\text{Mor}_{\mathbf{B}_{\mathcal{K}}} = \bigcup_{I \subseteq J} U_{IJ}$  are defined by the coordinate changes.

- ▶ The **cocycle condition** ensures that **composition** is possible, i.e. if  $\phi_{JK} \circ \phi_{IJ}(x)$  is defined for  $x \in U_{IJ}$  so is  $\phi_{IK}(x)$  and they are equal.
- ▶ In practice, one can only construct **weak atlases** with the **weak cocycle condition**, i.e. whenever both maps are defined, they are equal.
- ▶ We also want the **realization**  $|\mathcal{K}| := \bigcup_I U_I / \sim$  of  $\mathbf{B}_{\mathcal{K}}$  to have good properties eg Hausdorff, a well-behaved metric...

**Proposition** ([MW1], §6): *A weak Kuranishi atlas can be **tamed** to form a Kuranishi atlas  $\mathcal{K}$  with a “nice” realization  $|\mathcal{K}|$ .*

## From (weak) Kuranishi category to VFC (no isotropy): 11.

[MW1] **Theorem B.** *Let  $\mathcal{K}$  be an oriented,  $d$ -dimensional, weak, additive Kuranishi atlas with trivial isotropy groups on a compact metrizable space  $X$ . Then  $\mathcal{K}$  determines a **cobordism class of smooth, oriented, compact manifolds**, and an element  $[X]_{\mathcal{K}}^{\text{vir}}$  in the Čech homology group  $\check{H}_d(X; \mathbb{Q})$ . Both depend only on the **cobordism class of  $\mathcal{K}$** .*

The class  $[X]_{\mathcal{K}}^{\text{vir}}$  is represented by **the zero set  $Z(s + \nu)$**  – which is a manifold – **of a transverse perturbation  $|s + \nu|$**  of the section  $|s|$  of  $|\text{proj}| : |\mathbf{E}_{\mathcal{K}}| \rightarrow |\mathcal{K}|$ .

The perturbation  $\nu$  is tricky to construct: there is an inclusion  $\iota_X : X \rightarrow |\mathcal{K}|$  with image equal to  $Z(s)$ , but  **$Z(s)$  does NOT have compact neighbourhood in  $|\mathcal{K}|$** ; so need to work to ensure that  $Z(s + \nu)$  is **compact**.

Recall: An atlas is:  $\mathcal{K} = (\mathbf{K}_I, \widehat{\phi}_{IJ})$  where  $(\mathbf{K}_i)$  is a **covering family**,  $\mathbf{K}_I$  are **sum charts**, and each  $\widehat{\phi}_{IJ} : \mathbf{K}_I \rightarrow \mathbf{K}_J$  is a **coordinate change** over  $F_J$  with cocycle condition for  $I \subset J \subset K$ . When there is no isotropy,  $\widehat{\phi}_{IJ}$  is a **restriction** to  $U_{IJ} \subset U_I$  followed by an **"inclusion"**  $\phi_{IJ} : U_{IJ} \rightarrow U_J$ . With isotropy, the picture changes a little:

For  $I \subset J$ , the group  $\Gamma_J := \prod_{i \in J} \Gamma_i$  of  $\mathbf{K}_J$  splits as  $\Gamma_J = \Gamma_I \times \Gamma_{J \setminus I}$ .

The **coordinate change** is given by a subset  $\widetilde{U}_{IJ} \subset U_J$  where

- ▶  $\widetilde{U}_{IJ}$  is  $\Gamma_J$  invariant, where  $\Gamma_{J \setminus I}$  acts freely;
- ▶ the quotient  $\widetilde{U}_{IJ} / \Gamma_{J \setminus I}$  can be identified  $\Gamma_I$ -equivar. with  $U_{IJ} \subset U_I$ ; we get **equivariant covering map**  $\rho_{IJ} : \widetilde{U}_{IJ} \rightarrow U_{IJ}$  that **intertwines  $s, \psi$** .
- ▶ the category  $\mathbf{B}_{\mathcal{K}}$  has morphisms  $\widetilde{U}_{IJ} \times \Gamma_I$  with

$$s \times t : \widetilde{U}_{IJ} \times \Gamma_I \ni (x, \gamma_I) \mapsto (\gamma_I^*(\rho_{IJ}(x)), x) \in U_I \times U_J,$$

(these are morphisms from a subset of  $U_I$  into  $U_J$ , coming from the group actions and coord changes)

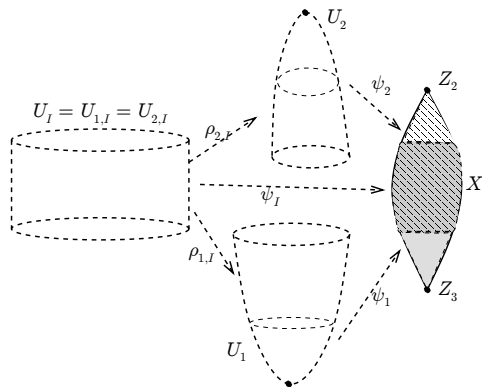
The **intermediate chart**  $\underline{K}_I$  has no isotropy, but has **orbifold domain and bundle**:

$$\underline{U}_I := U_I / \Gamma_I, \quad \underline{U}_I \times E_I := U_I \times E_I / \Gamma_I; \quad \pi_I : U_I \rightarrow \underline{U}_I.$$

A Kur. atlas  $\mathcal{K}$  has an **intermediate domain category**  $\underline{\mathbf{B}}_{\mathcal{K}}$  where

$$\text{Obj}_{\underline{\mathbf{B}}_{\mathcal{K}}} = \bigcup_I \underline{U}_I, \quad \text{Mor}_{\underline{\mathbf{B}}_{\mathcal{K}}} = \bigcup_{I \subset J} \underline{U}_{IJ}, \quad \text{where } \underline{U}_{IJ} = \pi_J(\tilde{U}_{IJ}) \subset \underline{U}_J.$$

- ▶ The functor  $\mathbf{B}_{\mathcal{K}} \rightarrow \underline{\mathbf{B}}_{\mathcal{K}}$  induces a **proper map** on objects and morphisms. (inverse images of compact sets are compact).
- ▶ The previous work for the “no isotropy” case applies to  $\underline{\mathbf{B}}_{\mathcal{K}}$  and then lifts to  $\mathbf{B}_{\mathcal{K}}$ . So we can construct **tamings and (multi)sections** as before.
- ▶ Thus get **VFC represented by a weighted branched manifold**, well defined up to cobordism; completing the abstract theory.



**Figure :**  $X$  is  $S^2$  with **two orbifold points of orders 2, 3**. There are **two basic charts**  $(U_1, \mathbb{Z}_3), (U_2, \mathbb{Z}_2)$  with images discs  $\underline{U}_i \subset X$ , and **one transition chart**  $(U_I, \mathbb{Z}_2 \times \mathbb{Z}_3)$  (where  $I = \{1, 2\}$ ) with image the **annulus**  $\underline{U}_I = \underline{U}_1 \cap \underline{U}_2$ .

$$X = \{f : S^2 \rightarrow (M, J) \mid \bar{\partial}_J f = 0, f_*([S^2]) = A\} / G_\infty.$$

To make chart at  $[f_0] \in X$  with  $\Gamma = \text{Stab}([f_0])$ , must

- ▶ **Stabilize domain** by adding two marked points 0, 1 and **fix parametrization**  $f_0$  by fixing  $f_0(0), f_0(1)$ ; This is achieved **via slicing conditions**: i.e. Choose  $Q^{2n-2} \subset M$  transverse to  $\text{im } f_0$ , and require  $f_0(0), f_0(1) \in Q$ ;
- ▶ Extend  $v^0 := 0, v^1 = 1$  to a (minimal)  **$\Gamma$ -invariant tuple**  $\vec{v} = (v^0, \dots, v^{L-1})$ ;
- ▶ Choose  **$\Gamma$ -invariant set of disjoint disc nbhds**  $D^{f_0}(v^\ell) \subset S^2$  s.t.  $f_0^{-1}(Q) \cap D^{f_0}(v^\ell) = \{v^\ell\} \forall \ell$ ;
- ▶ Choose **obstruction space**  $E_0 \subset C^\infty\text{-sect}(\mathcal{H})$  where  $\mathcal{H} \rightarrow S^2 \times M$  is bundle with  $\mathcal{H}_{(z,x)} = \text{Hom}_J^{0,1}(T_z S^2, T_x M)$  s.t.  $E_0$  covers  $\text{coker } D_{f_0}(\bar{\partial}_J)$
- ▶ This gives a “geometrically defined” obstruction space  $\vec{E} := \bigoplus_{\gamma \in \Gamma} E_0^\gamma$ , the sum of  $|\Gamma|$  copies of  $E_0$ . (“Abstract” obstruction spaces do not usually transform  $C^1$  smoothly under coordinate changes.)

- ▶ Given  $\vec{w} = (w^0, \dots, w^{L-1}) \in (S^2)^L$  define  $\phi_{\gamma, \vec{w}} \in G_\infty$  to be the unique map s.t.  $0 \mapsto w^{\gamma(0)}, 1 \mapsto w^{\gamma(1)}$ .
- ▶ Define  $U \subset \vec{E} \times (S^2)^L \times \text{nbhd}(f_0)$  by “Fredholm stabilization”:

$$U = \left\{ (\vec{v}, \vec{w}, f) \mid \bar{\partial}_J f = \sum_{\gamma} (\phi_{\gamma, \vec{w}}^{-1})^* \nu^{\gamma} \Big|_{\text{graph} f}, \right. \\ \left. \begin{array}{l} \text{(normalization)} \ w^0 = 0, w^1 = 1, \\ \text{(slicing)} \ w^\ell = f^{-1}(Q) \cap D^{f_0}(v^\ell) \end{array} \right\}$$

- ▶ **Action of  $\Gamma$ :**  $(\vec{v}, \vec{w}, f) \mapsto \gamma^*(\vec{v}, \vec{w}, f) = (\gamma^*(\vec{v}), \gamma^*(\vec{w}), f \circ \phi_{\gamma, \vec{w}})$ , where
  - $(\gamma^*(\vec{v}))^\ell = \nu^{\gamma(\ell)} =: (\gamma \cdot \vec{v})^\ell$ ,
  - $(\gamma^*(\vec{w}))^\ell = \phi_{\gamma, \vec{w}}^{-1}(w^{\gamma(\ell)}) = \phi_{\gamma, \vec{w}}^{-1}((\gamma \cdot \vec{w})^\ell)$ . (This preserves slicing conditions and normalization  $\gamma^*(\vec{w}) = (0, 1, \dots)$ : you can't just permute the tuple  $\vec{w}$  since we have normalized.)
- ▶ The chart is  $(U, \vec{E}, \Gamma, s, \psi)$  where  $s(\vec{v}, \vec{w}, f) = \vec{v} \in \vec{E}$ ,  $\psi(\vec{v}, \vec{w}, f) = [f]$ .



Given  $(U_i, \vec{E}_i, \Gamma_i, s_i, \psi_i)$ , pick  $i_0 \in \{1, 2\}$  and define  $\mathbf{K}_I$  for  $I = \{1, 2\}$  with domain  $i_0$ -normalized; so  $U_I \subset \mathcal{W}_{I, i_0}$  where

$$\mathcal{W}_{I, i_0} = \{(\vec{\nu}, \vec{w}, f) \in \vec{E}_1 \times \vec{E}_2 \times (S^2)^{L_1+L_2} \times \text{nbhd}(f_0) \mid w_{i_0}^0 = 0, w_{i_0}^1 = 1\}.$$

$$\blacktriangleright U_I := \left\{ (\vec{\nu}, \vec{w}, f) \mid \bar{\partial}_J f = \sum_{i=1,2, \gamma \in \Gamma_i} (\phi_{\gamma, \vec{w}_i}^{-1})^* \nu_i^\gamma \Big|_{\text{graph} f}, f(w_i^\ell) \in Q_i \right\}$$

(here  $U_I \subset \mathcal{W}_{I, i_0}$ ; also must specify the ordering of the tuple  $\vec{w}_j, j \neq i_0$ , more carefully)

$\blacktriangleright$  Action of  $\Gamma_I$  depends on  $i_0$ : with  $i_0 = 1$

$\blacktriangleright \gamma \in \Gamma_1$  acts by perm. and reparametrization (to preserve normalization)

$$\gamma^*(\vec{\nu}_1, \vec{\nu}_2, \vec{w}_1, \vec{w}_2, f) = (\gamma \cdot \vec{\nu}_1, \vec{\nu}_2, \phi_{\gamma, \vec{w}_1}^{-1}(\gamma \cdot \vec{w}_1), \phi_{\gamma, \vec{w}_1}^{-1}(\vec{w}_2), f \circ \phi_{\gamma, \vec{w}_1}),$$

$\blacktriangleright \gamma \in \Gamma_2$  acts just by permutation

$$\gamma^*(\vec{\nu}_1, \vec{\nu}_2, \vec{w}_1, \vec{w}_2, f) = (\vec{\nu}_1, \gamma \cdot \vec{\nu}_2, \vec{w}_1, \gamma \cdot \vec{w}_2, f),$$

$\blacktriangleright$  the projection  $\rho_{1,I} : U_I \supset \tilde{U}_{1,I} \rightarrow U_1$  is the forgetful map  $(\vec{\nu}_1, \vec{\nu}_2, \vec{w}_1, \vec{w}_2, f) \mapsto (\vec{\nu}_1, \vec{w}_1, f)$  (and for  $i = 2$  is forgetful map plus renormalization. i.e. All elements of the construction are very natural.)

- ▶ The previous slides attempt to explain how to construct a Kuranishi atlas near the parts of  $X$  represented by curves with smooth domains.
- ▶ It remains to deal with **nodal curves**. Instead of using a fancy gluing theorem that would give a smooth structure to the domains  $U$  near a nodal curve, we will use the standard theorem in [Mc-Sal] that gives **continuity in the gluing parameters  $a$**  but with evaluation maps **depending  $C^1$  on  $a$** . This is enough to give a Kuranishi atlas whose domains are **stratified smooth**. [Details still to be written, should be pretty straightforward]
- ▶ An interesting **special case** is when there is a **regular  $J$**  (e.g. for a space of genus zero stable maps into  $\mathbb{C}P^n$ .) Then there is an orbifold Kuranishi atlas (i.e. all  $E$  trivial) [Details still to be written]
- ▶ Potential generalizations: to curves in **manifolds with  $S^1$  action**; to curves with intrinsic Lie group symmetries (e.g. **Hamiltonian Floer homology** with time independent Hamiltonian [needs extra work to deal with the boundary]), to Gromov–Witten invariants for **symplectic orbifolds** . . . [none of this done at all]

[CLW13] Bohui Chen, An-Min Li, and Bai-Ling Wang, Virtual neighborhood technique for pseudo-holomorphic spheres, arXiv:1306.3276.

[FOOO12] K. Fukaya, Y.-G. Oh, H. Ohta, and K. Ono, Technical detail on Kuranishi structure and Virtual Fundamental Chain, arXiv:1209.4410.

[HWZ4] H. Hofer, K. Wysocki, and E. Zehnder, Applications of Polyfold theory I: The Polyfolds of Gromov–Witten theory, arXiv:1107.2097.

[IP] E. Ionel and T. Parker, A natural Gromov–Witten fundamental class, arXiv:1302.3472

[Mc-Sal] D. McDuff and D.A. Salamon, *J-holomorphic curves and symplectic topology*, Colloquium Publications **52**, American Mathematical Society, Providence, RI, (2004), 2nd edition (2012).

[MW1] D. McDuff and K. Wehrheim Smooth Kuranishi atlases without isotropy, arXiv:1208.1340.

[MW2] D. McDuff and K. Wehrheim Smooth Kuranishi atlases with isotopy, in preparation